# Spanning Trees

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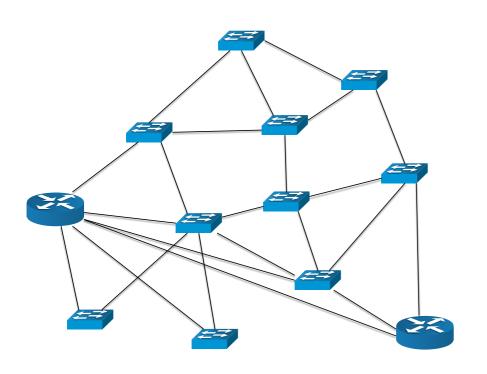
#### Problem

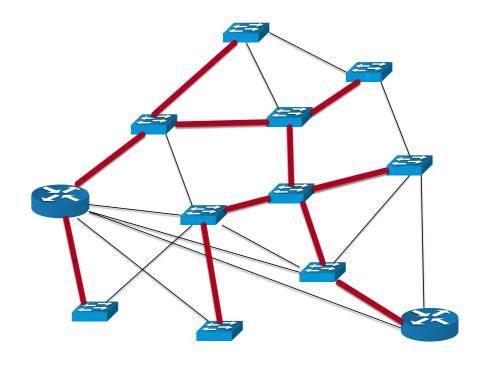
- Networking: LAN
  - Switches are connected by links
    - Cycles can create problems:
      - Broadcast radiation
        - A broadcast or multicast message is repeatedly received by the same switch and resend and resend and resend and resend ...

#### Problem

#### • Solution:

 Use an acyclic subgraph that contains all switches for broadcasting, multicasting, and in general for addressing purposes



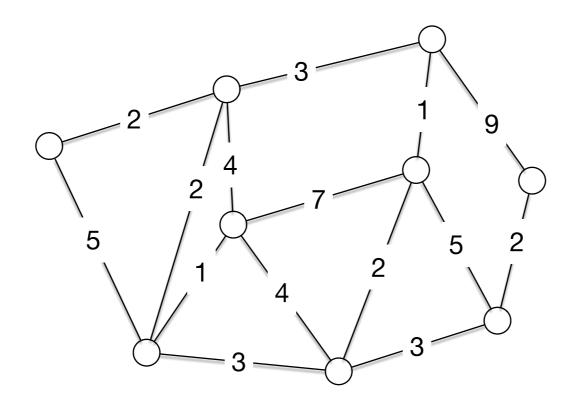


#### Trees

- A tree is a graph that is:
  - acyclic
  - connects all vertices

## Weighted Graphs

- We look at graphs where each edge has a weight
  - Depending on application, some weights can be negative or all weights have to be positive



# Weighted Graphs

• Other example:



- Given a weighted graph:
  - ullet Find a subset T of edges such that
    - connects all vertices
    - is acyclic
    - Total weight is minimal

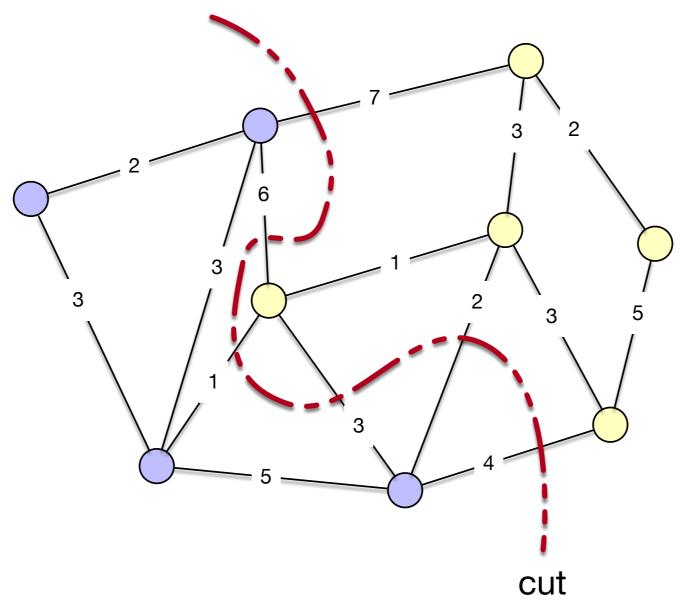
$$w(T) = \sum_{(u,v)\in T} w(u,v) \longrightarrow \infty$$

 Called a minimum weight spanning tree, but "weight" is usually omitted

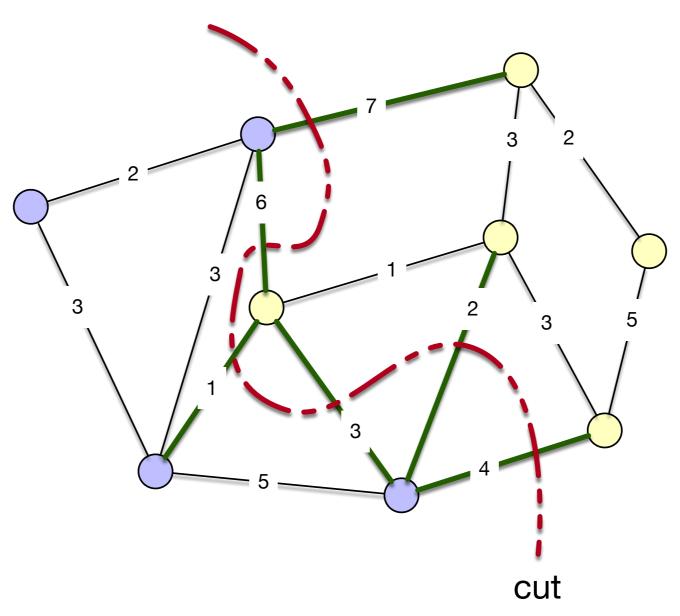
- Two greedy algorithms, Kruskal's and Prim's
- Use a loop invariant:
  - Let A be the set of edges currently selected
  - Invariant: A is a subset of some minimum spanning tree
  - At each step of the algorithm: only add an edge (u, v) if the invariant remains true after inserting the edge
  - Such an edge is a safe edge

- Generic MST algorithm
  - $1.A = \emptyset$
  - 2. While A is not a spanning tree
    - 1.Find a safe edge
    - 2.Add the safe edge to A
  - 3.Return A

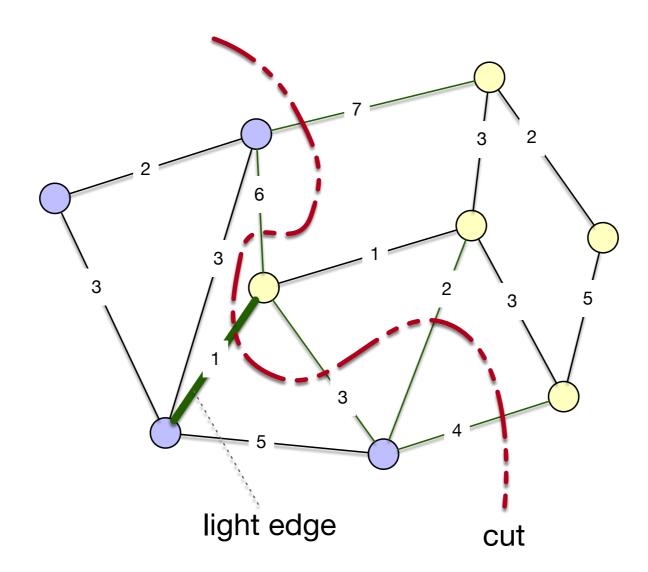
A cut is a partition of the vertices of the graph



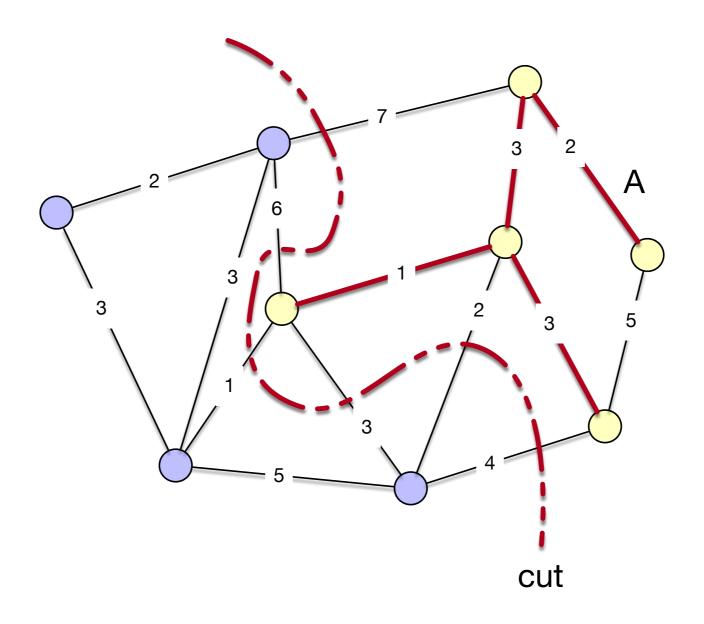
Edges can "cross the cut"



 Edges are "light" if the cross the cut and no other edge crossing the cut has a smaller weight

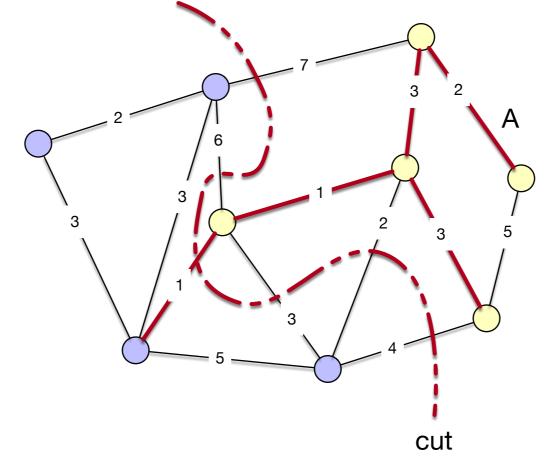


A cut respects A if no edge of A crosses the cut



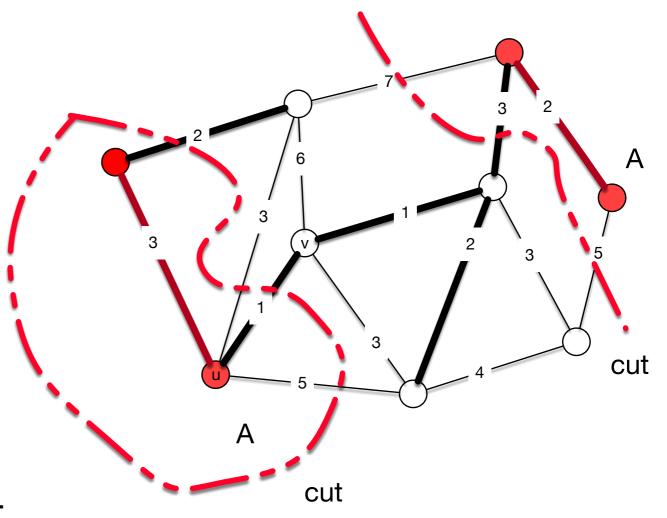
• Theorem: Let A be a subset of E included in some minimum spanning tree, let (S, E - S) be a cut respecting A and let (u, v) be a light edge crossing the cut. Then this

edge is safe



#### Proof:

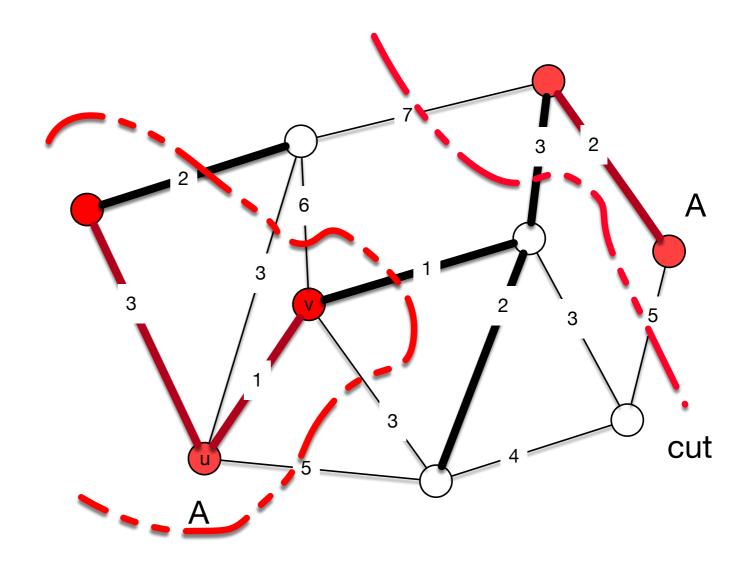
- We have a subgraph
   A that is part of a
   minimum spanning
   tree T
- We have a minimum weight crossing edge
   (u, v) crossing the cut that separates A from the rest of the graph



This set A has two different connected components and consists of red vertices

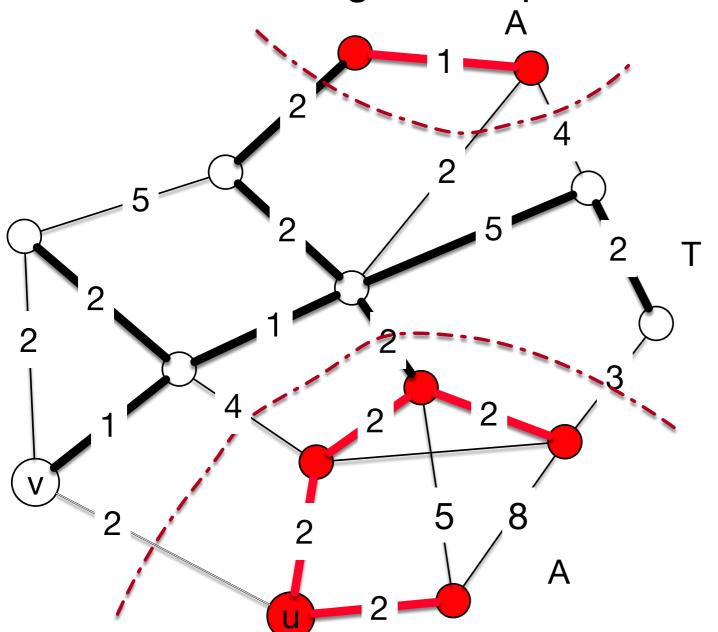
T is given by the fatter edges

- Case 1: The edge is part of T
- Then there is nothing to show since adding the edge still gives us a subgraph that is part of a minimum spanning tree



cut

Case 2: The edge is not part of T

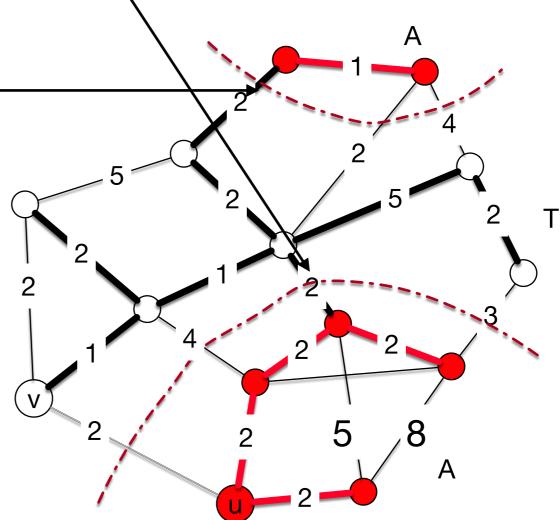


Edges and vertices in A are red Edges in T are fat This includes the red edges u and v are at the lower left

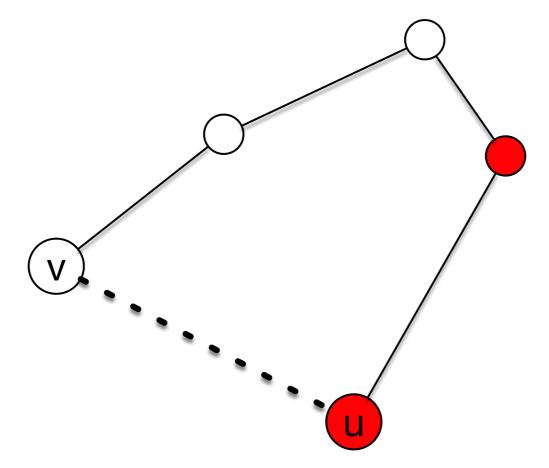
- In this case, we need to construct a new minimum weight spanning tree
- Observe that there has to be an edge of T that crosses the cut
  - Because we can travel from every node to every node in T and not all nodes are in A

• This edge in T that crosses the cut also has weight 2 in our example, but for sure, it has weight  $\geq$  the weight of (u, v)

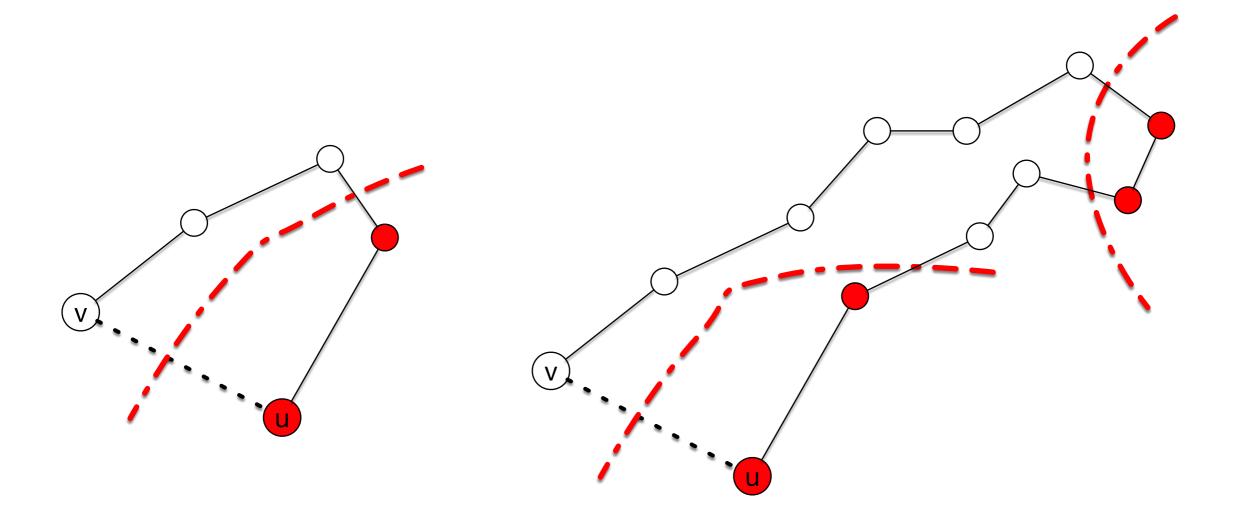
There is another edge



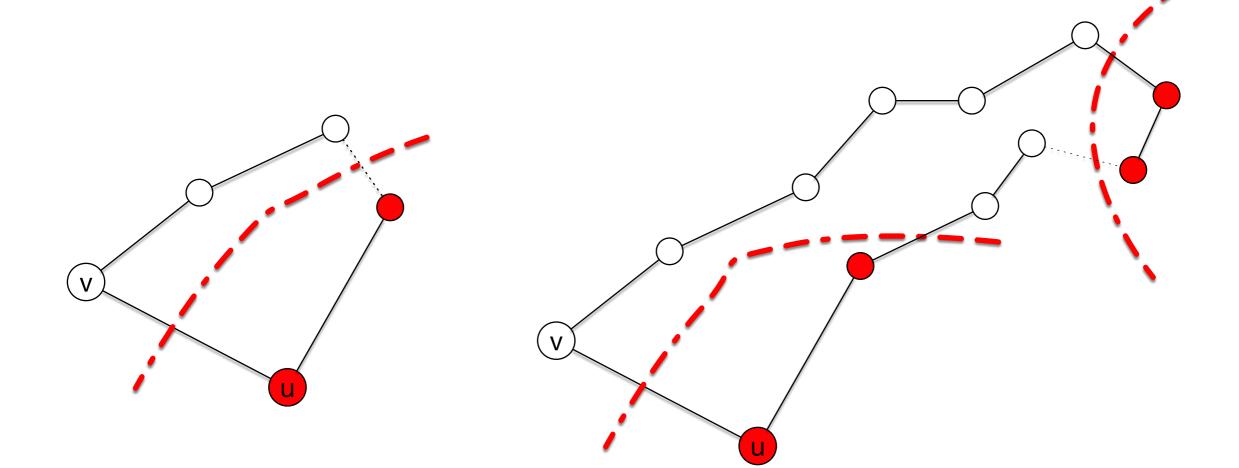
• There has to be a path from u to v in T because T is a spanning tree



 This path has to have at least one edge that crosses the cut

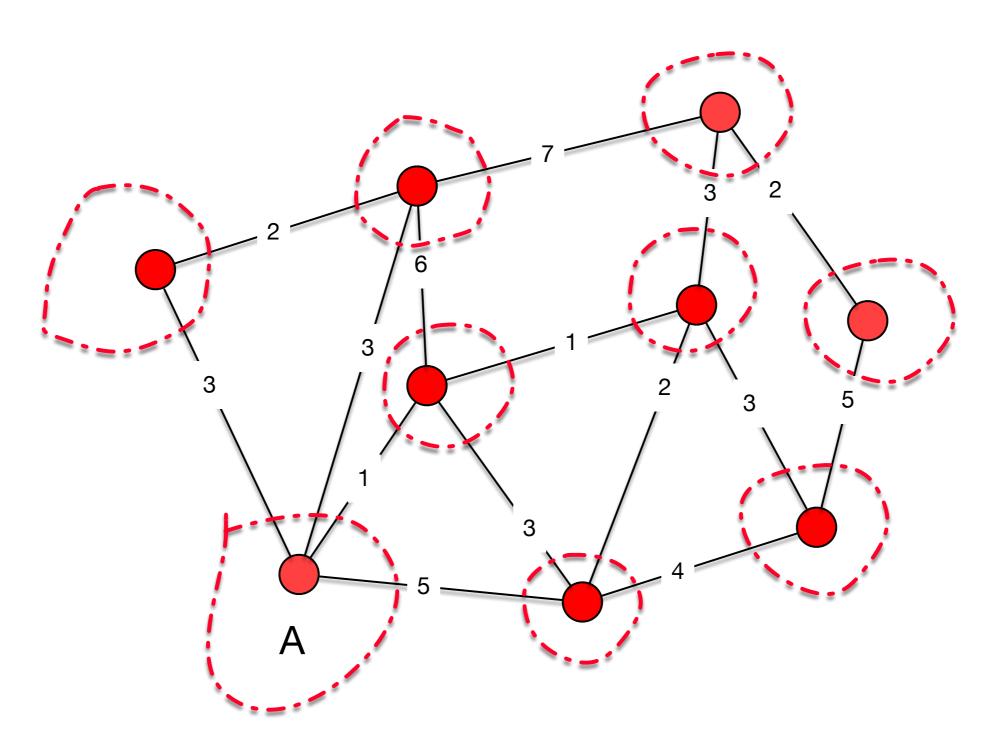


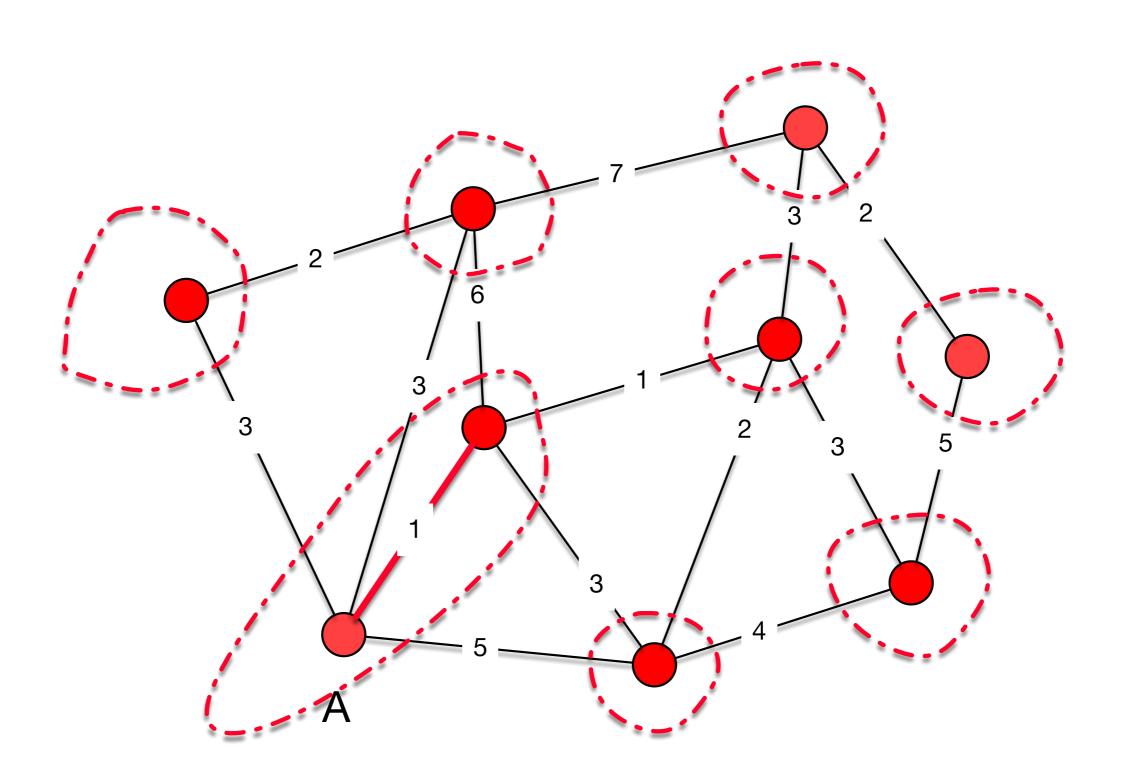
- Take one of these edges and replace it with (u, v) in T
- Call the result T'

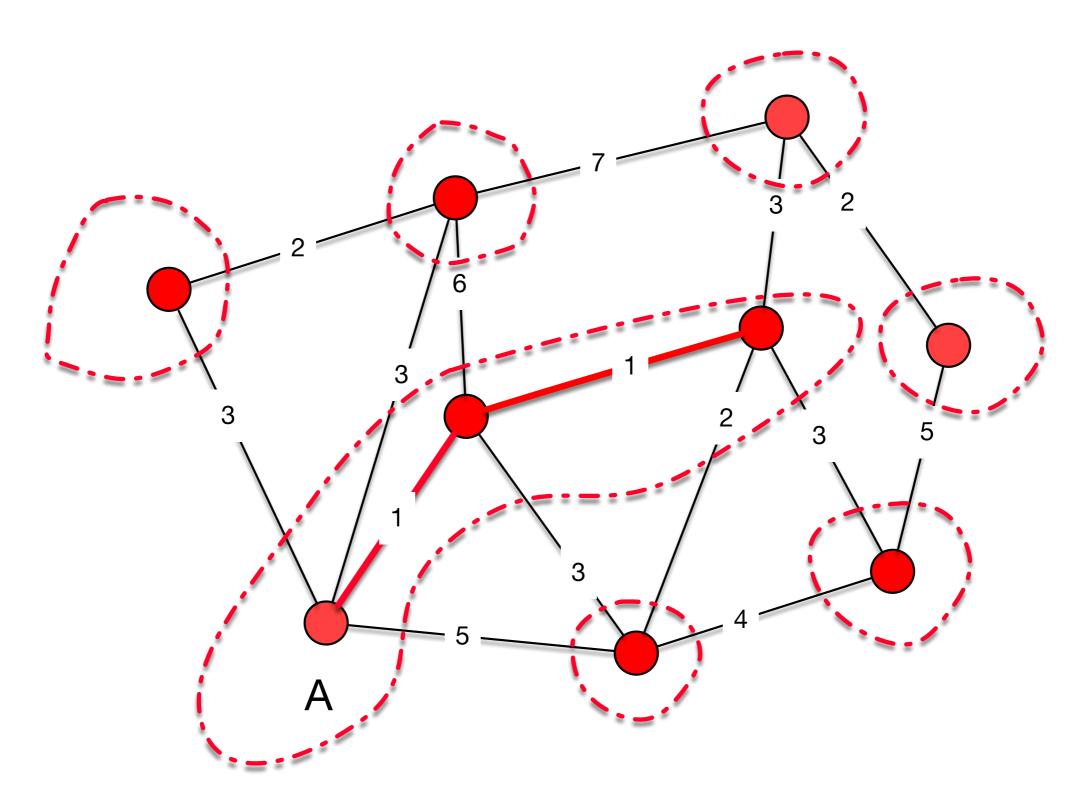


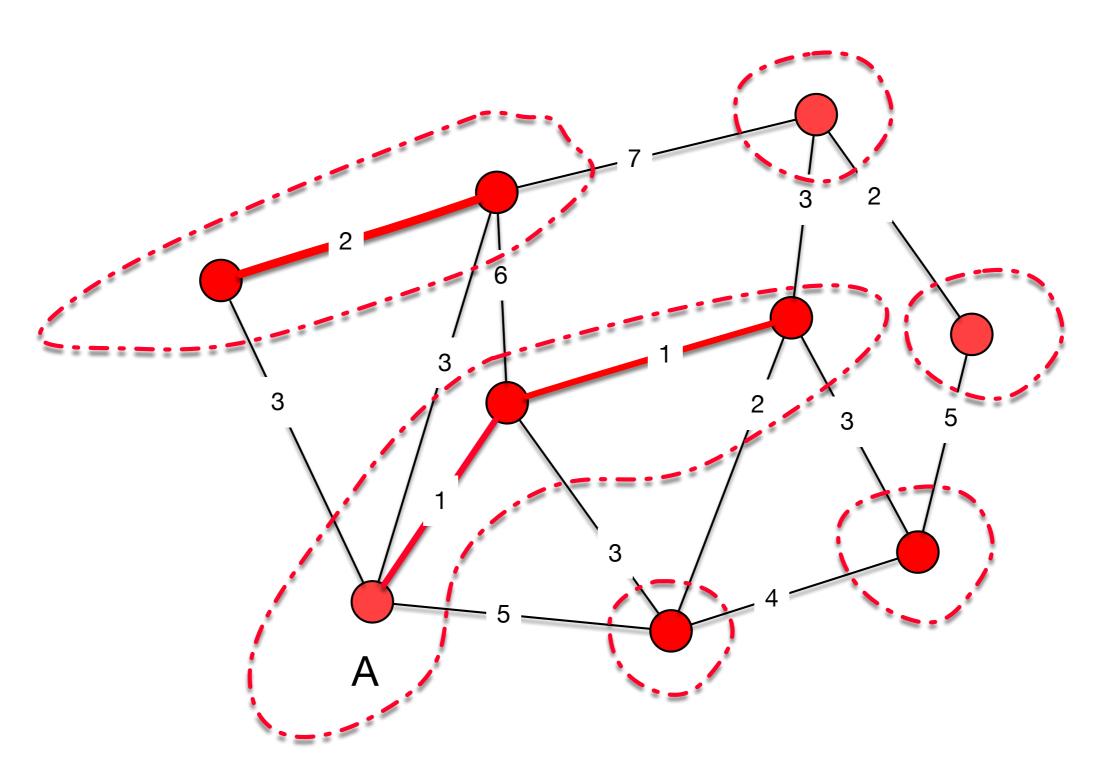
- T' still connects all of the vertices
  - If a, b are two vertices that are connected in T by the deleted edge:
    - Can reroute through the edge (u, v)
  - T' has a weight changed by replacing the weight of (u, v) with the weight of the deleted edge
    - But because the weight of (u, v) is minimal among all edges crossing the cut and the deleted edge also crossed the cut, T' weight can only be lower
- Thus, A after adding the edge (u, v) fulfills still the invariant. qed

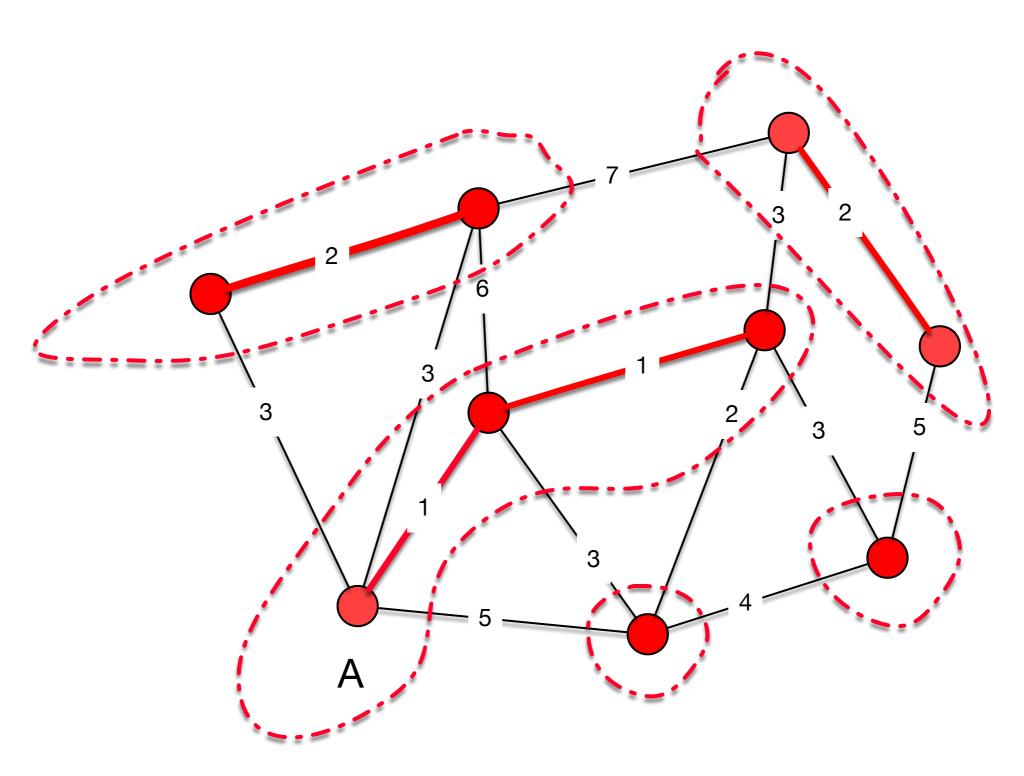
- Kruskal's algorithm works by joining subtrees
  - Start out with all vertices being their own subtrees
    - Thus, the cut is around all of the vertices
  - While we have more than one subtree:
    - We select a cutting edge (i.e. between different subtrees) with minimum weight
    - This combines two subtrees

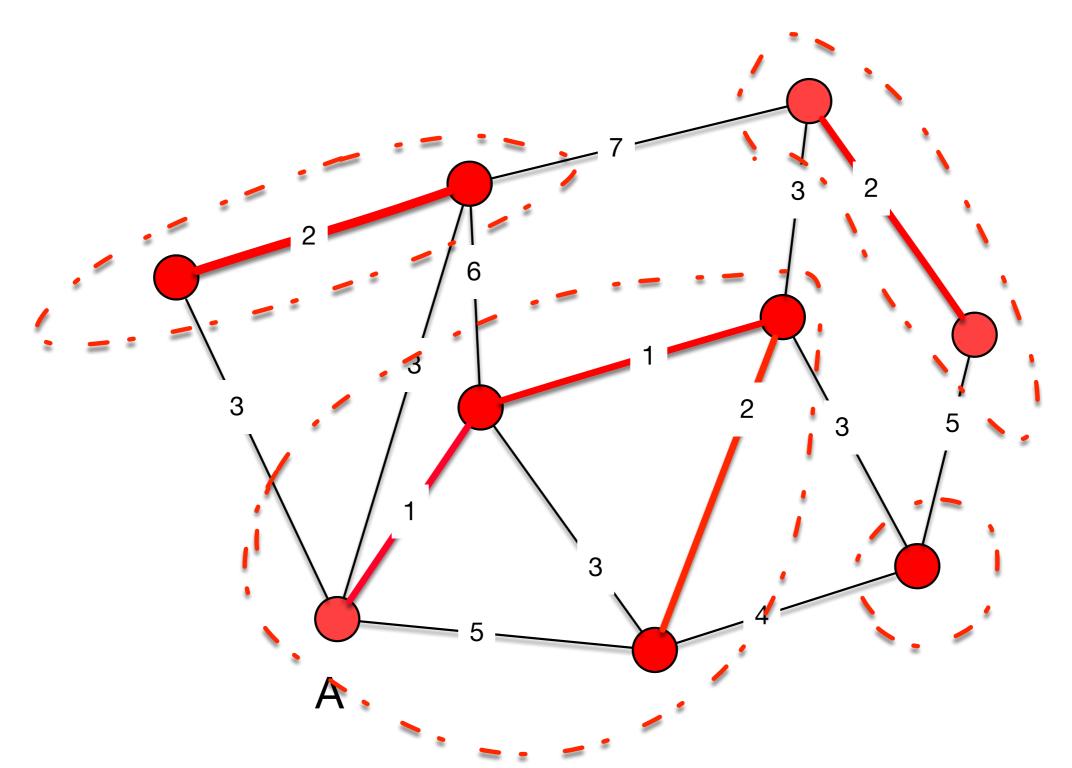


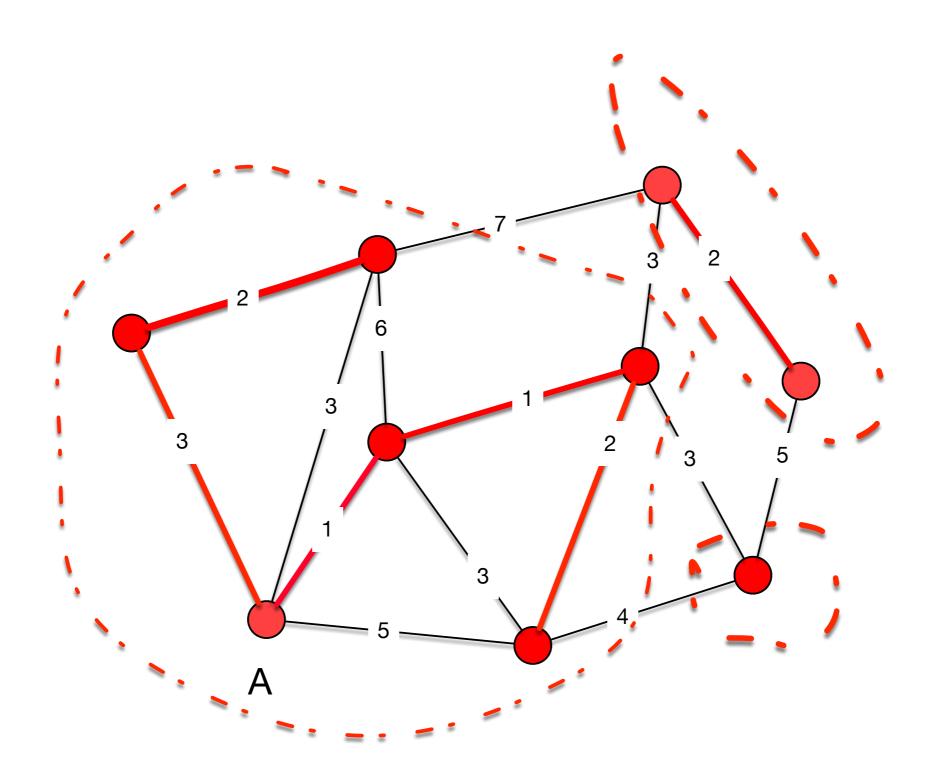


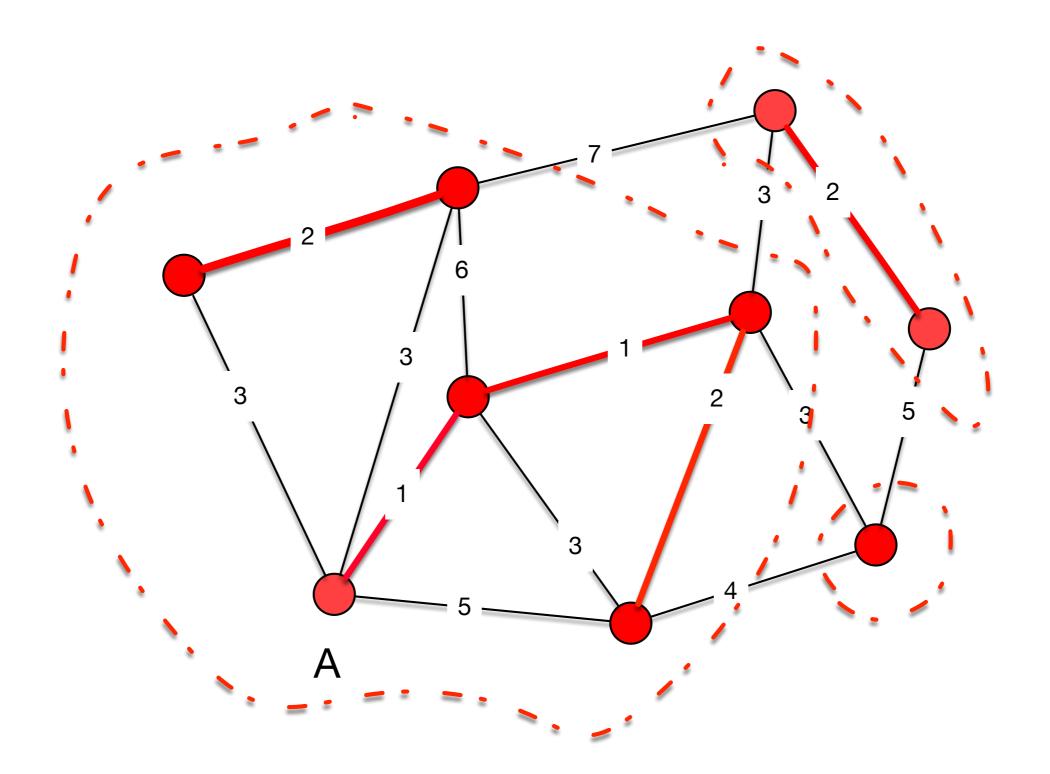


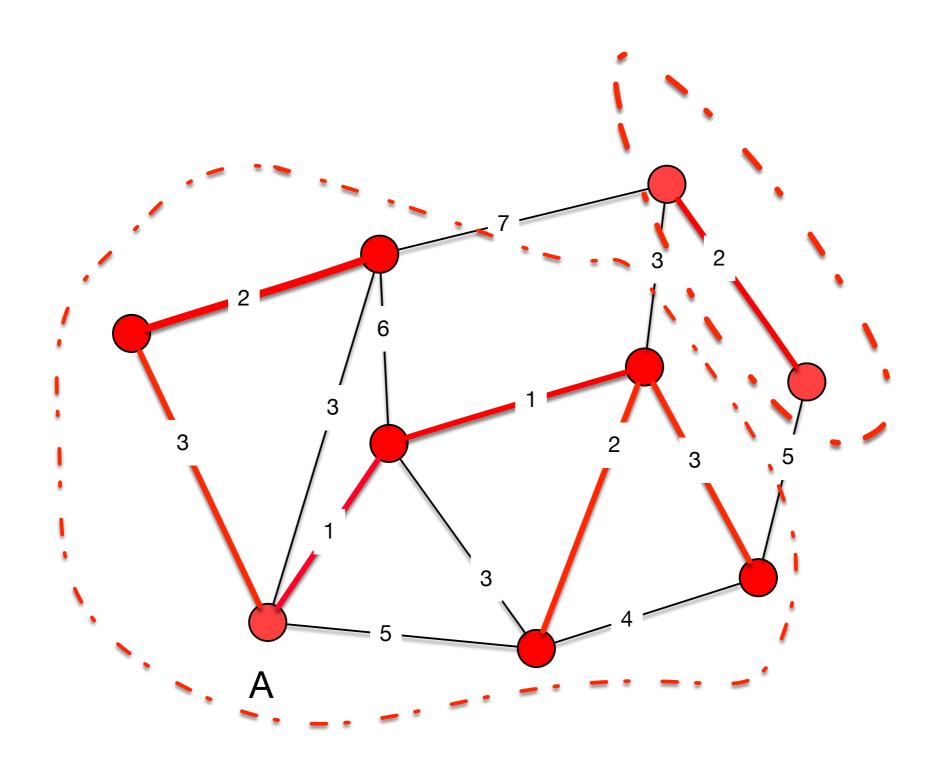


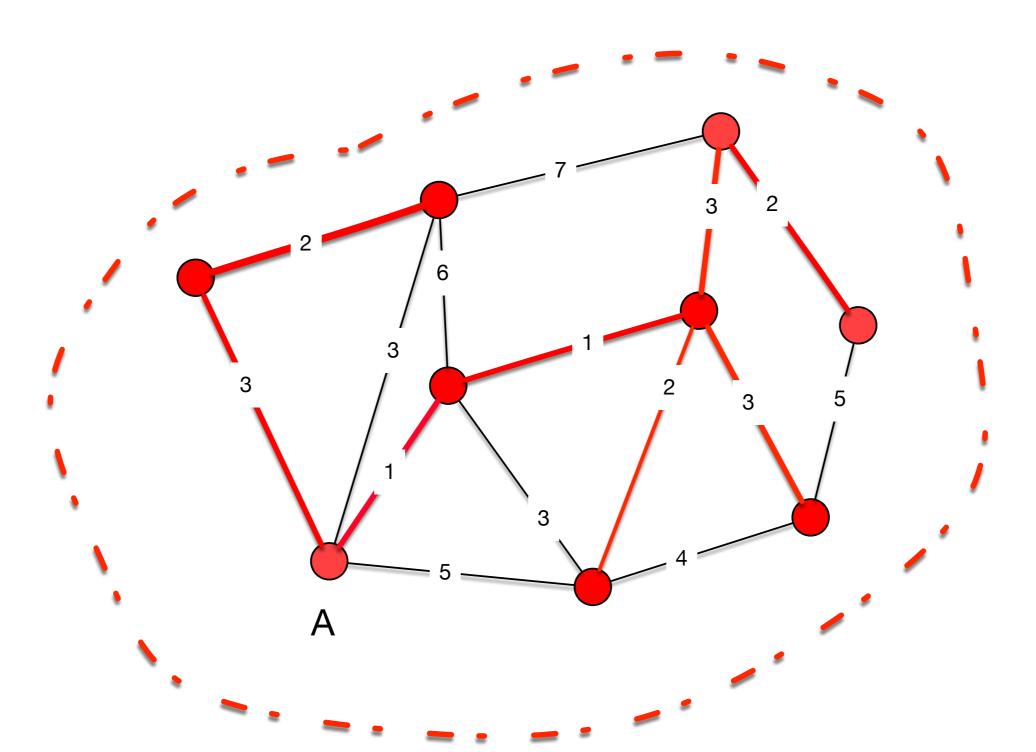










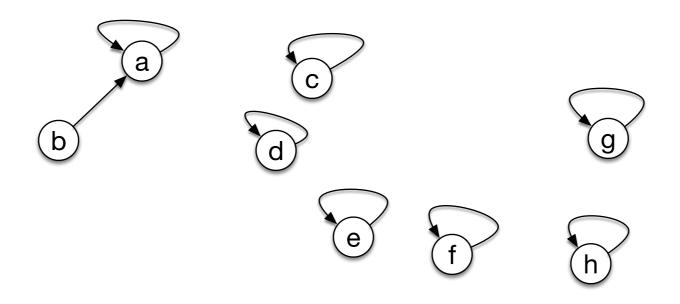


- Because Kruskal's algorithm only adds safe edges, it generates a minimum weight spanning tree
- How to organize it?
  - We can order all of the edges by weight
  - And then remove edges if they no longer are cutting edges
  - Best way:
    - Maintain vertices in the same subtree in a set
    - Determine quickly whether something is in a set

- Best solution known to humanity for the disjoint set problem:
  - have vertices organized by a directed edge to the "set leader"

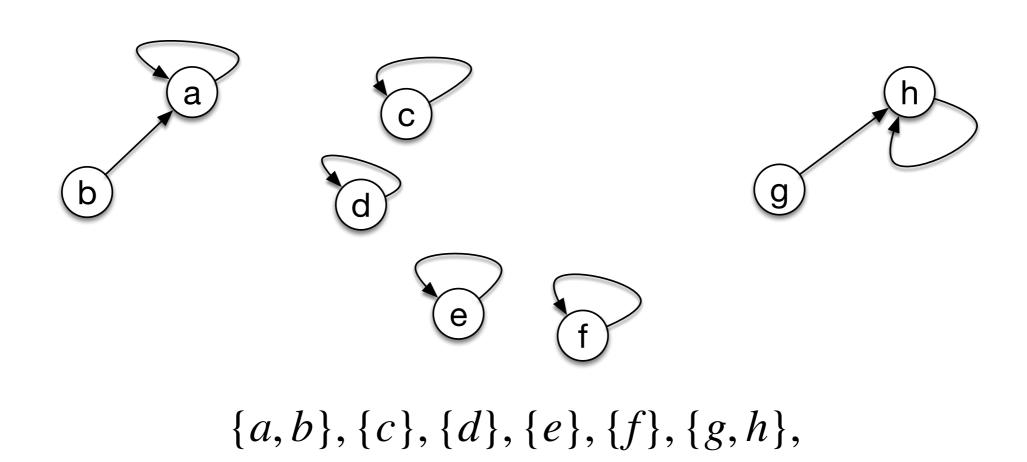
 $\{a\}, \{b\}, \{c\}, \{d\}, \{e\}, \{f\}, \{g\}, \{h\}$   $\begin{tabular}{c} \hline c \\ \hline d \\ \hline \end{tabular}$ 

• If we unite  $\{a\}$  and  $\{b\}$ , we have one point to the other

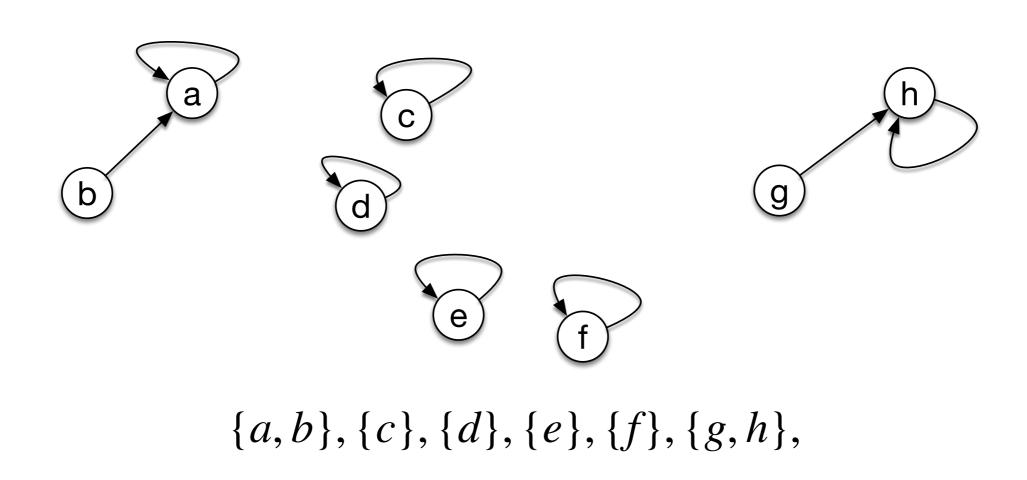


 ${a,b},{c},{d},{e},{f},{g},{h}$ 

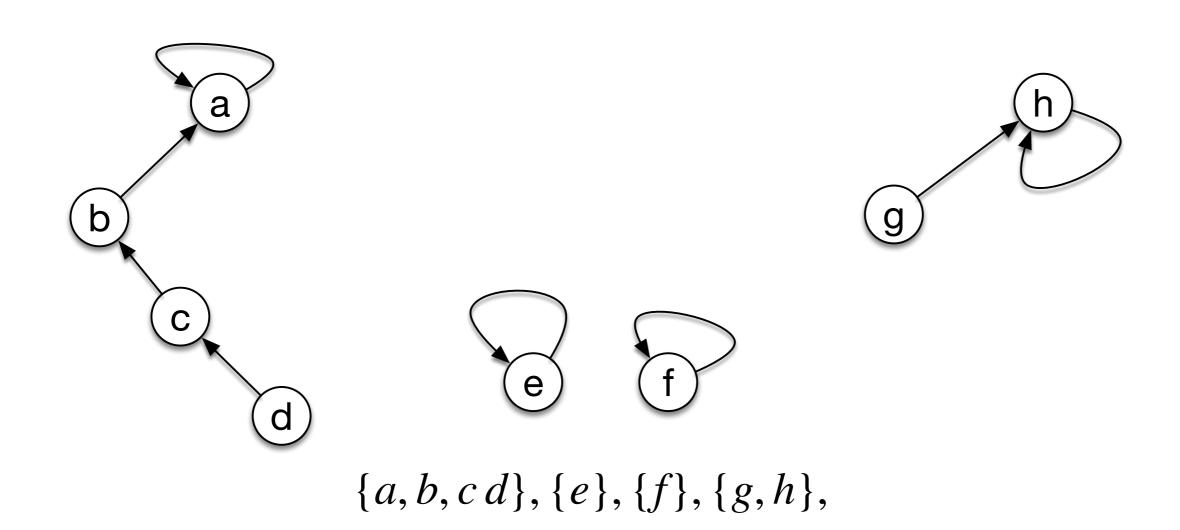
• Same if we unite  $\{g\}$  and  $\{h\}$ 



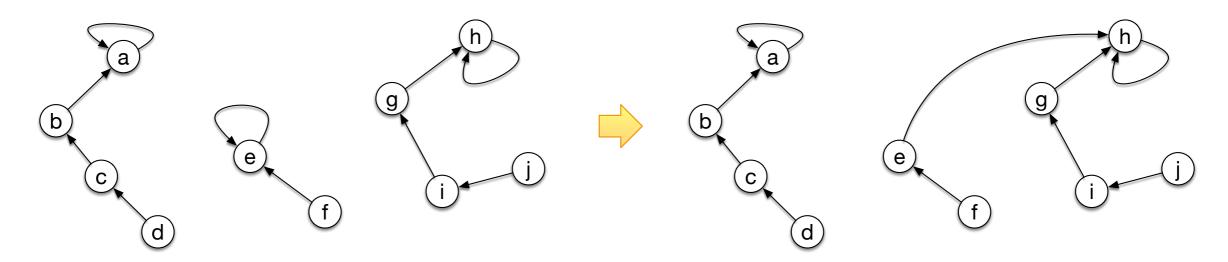
 If we ask whether b and g are in two different components, we follow the arrow and see whether the leaders are the same or not.



- This can be optimized:
  - There is the possibilities of having long chains

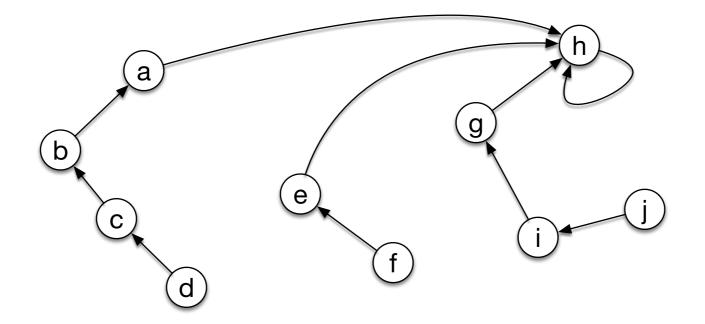


- When we join, we connect one leader to the other leader
  - Always make the larger set the head



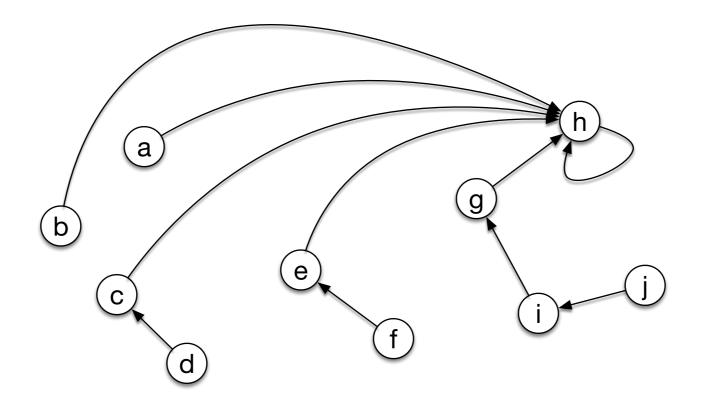
 ${a,b,cd}, {e,f} \cup {g,h,i,j},$ 

- When we do a look up:
  - What is the head of c?

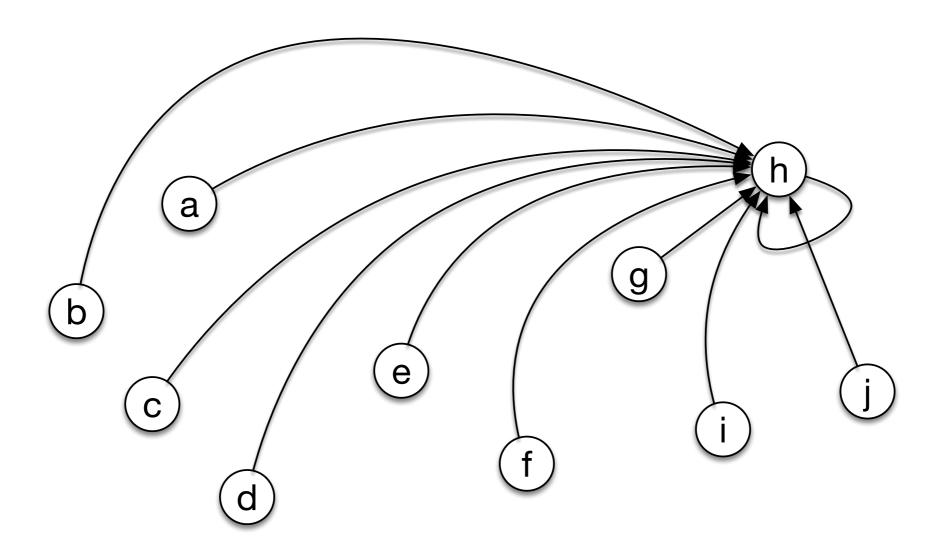


Follow three links to get to 'h'

- When we do a look up:
  - Reconnect the node and all we travel to directly to the head



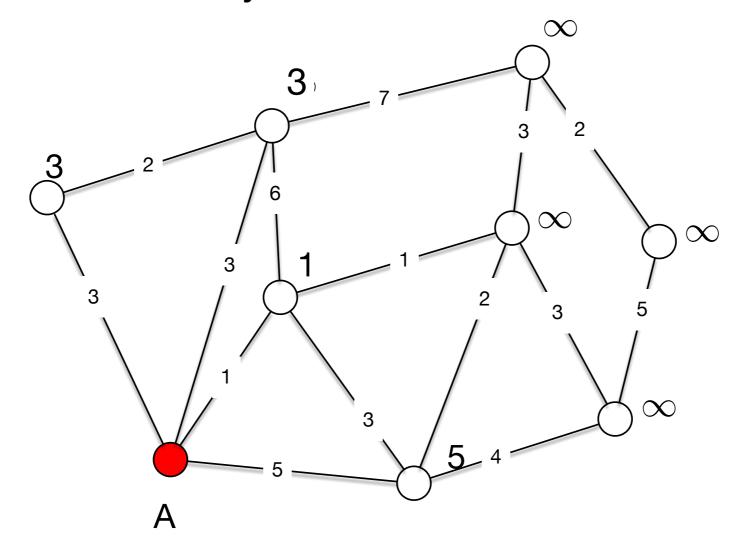
Best possible case: Every node points directly to the head



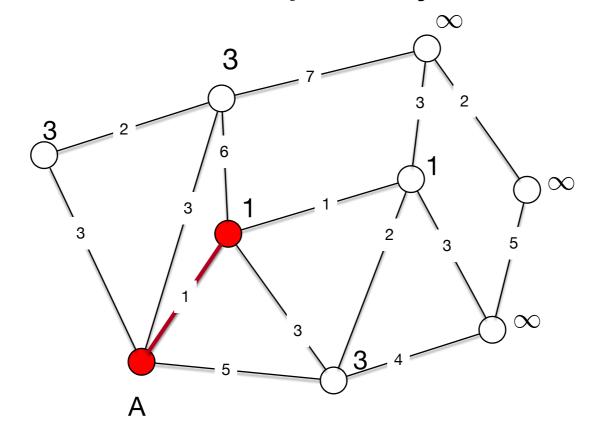
- With this "disjoint union data structure":
  - Maintaining the disjoint set data structure costs  $\alpha(|V|)$  per operation where  $\alpha$  is a function that grows very slowly
  - Kruskal's algorithm then runs in time  $O(|E|\log(|E|))$

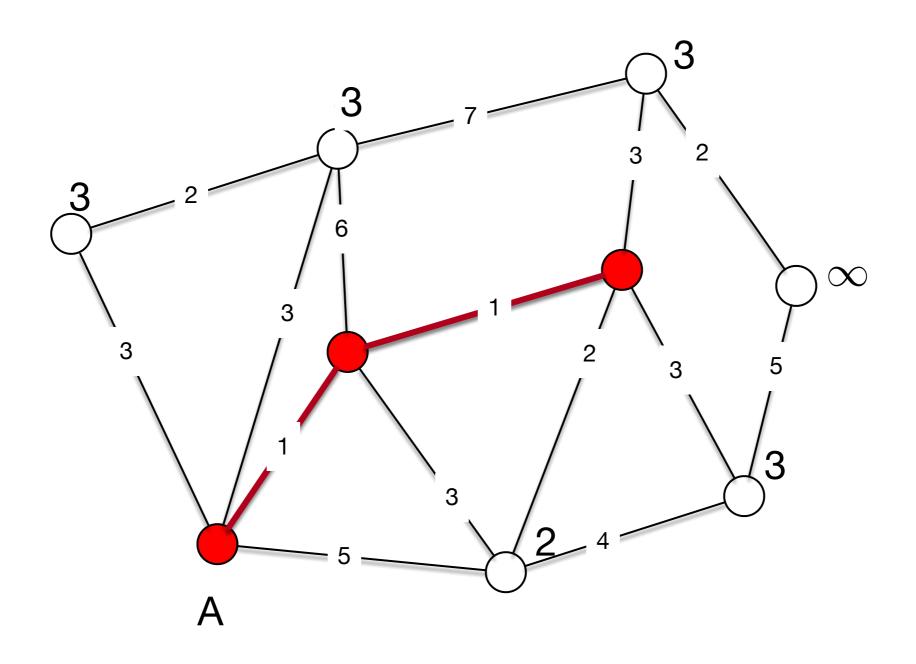
- Prim's algorithm starts A at a single node and then adds edges to it.
- Thus, the intermediate results are always connected
  - Maintain a priority queue of all other vertices
    - The vertices are ordered by distance to A

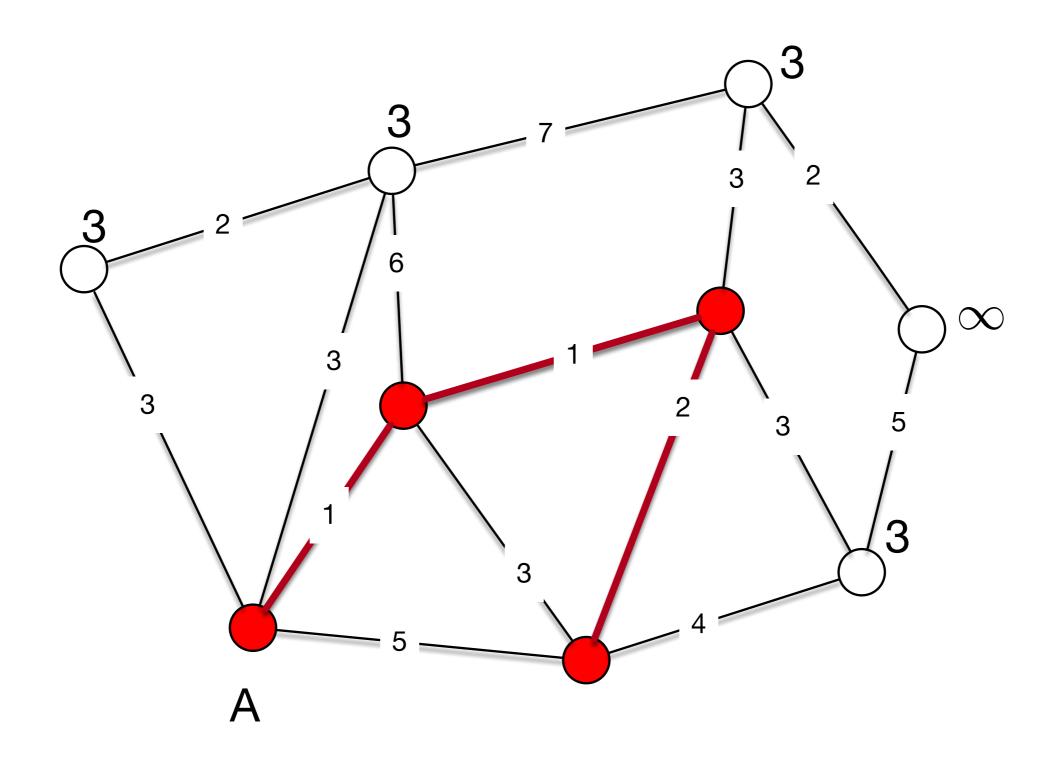
- We use the same example as before
- We can start at any node

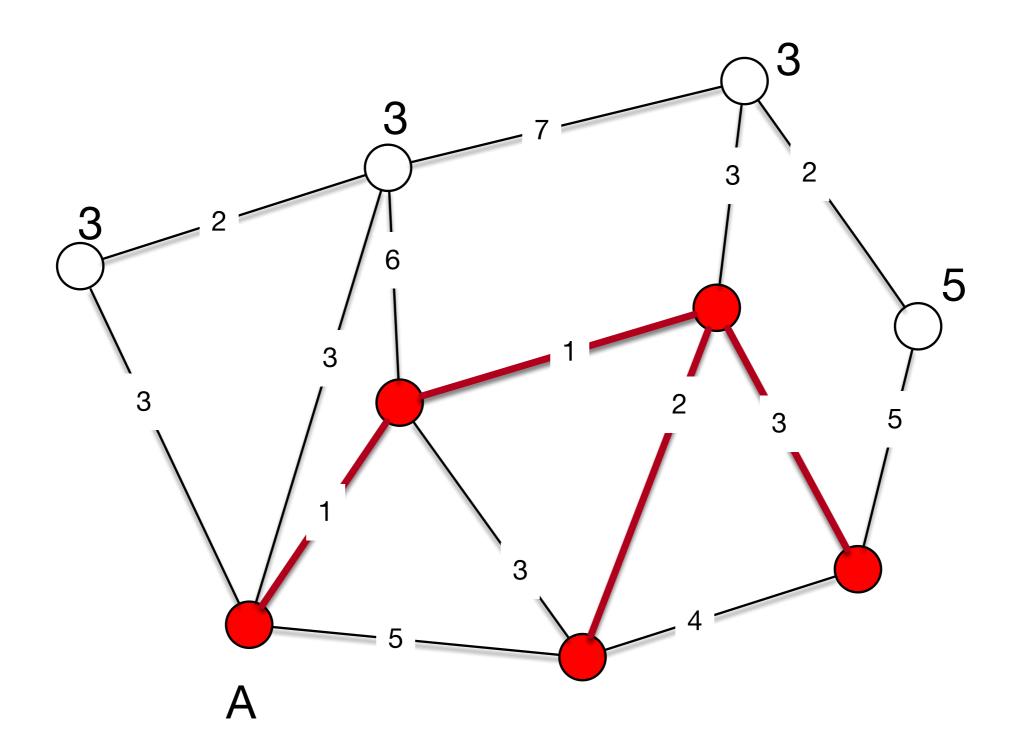


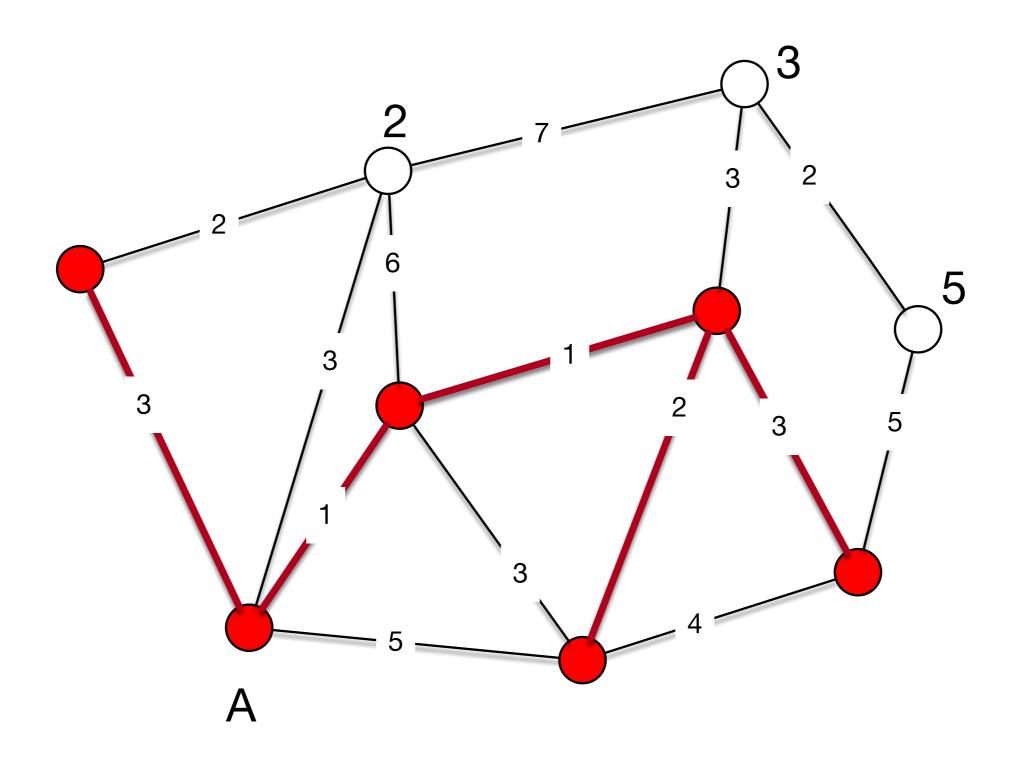
- The priority queue tells us which node to select
- After selecting edge and node, we need to update some nodes
- Namely those in the adjaceacy list of the new node

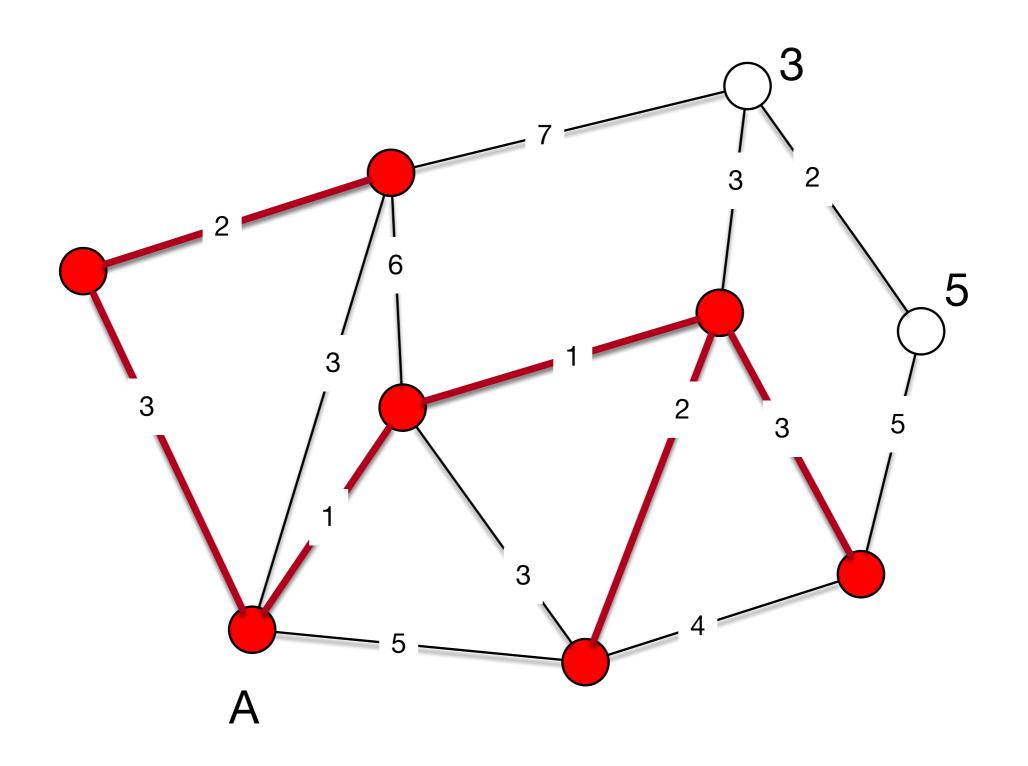


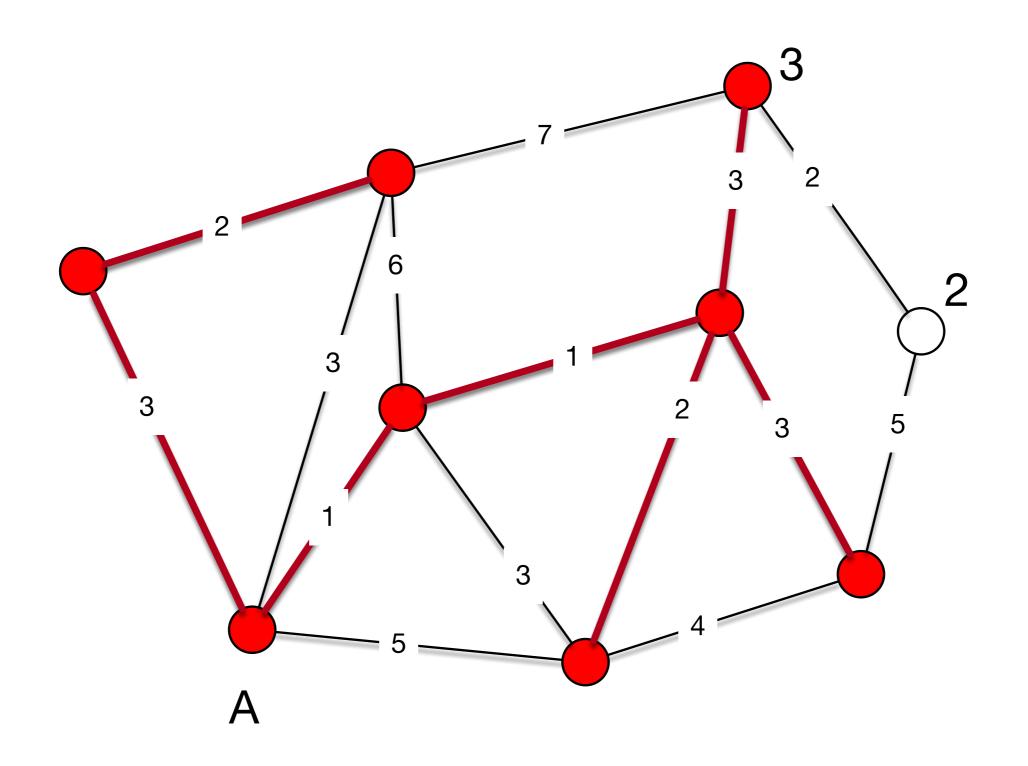


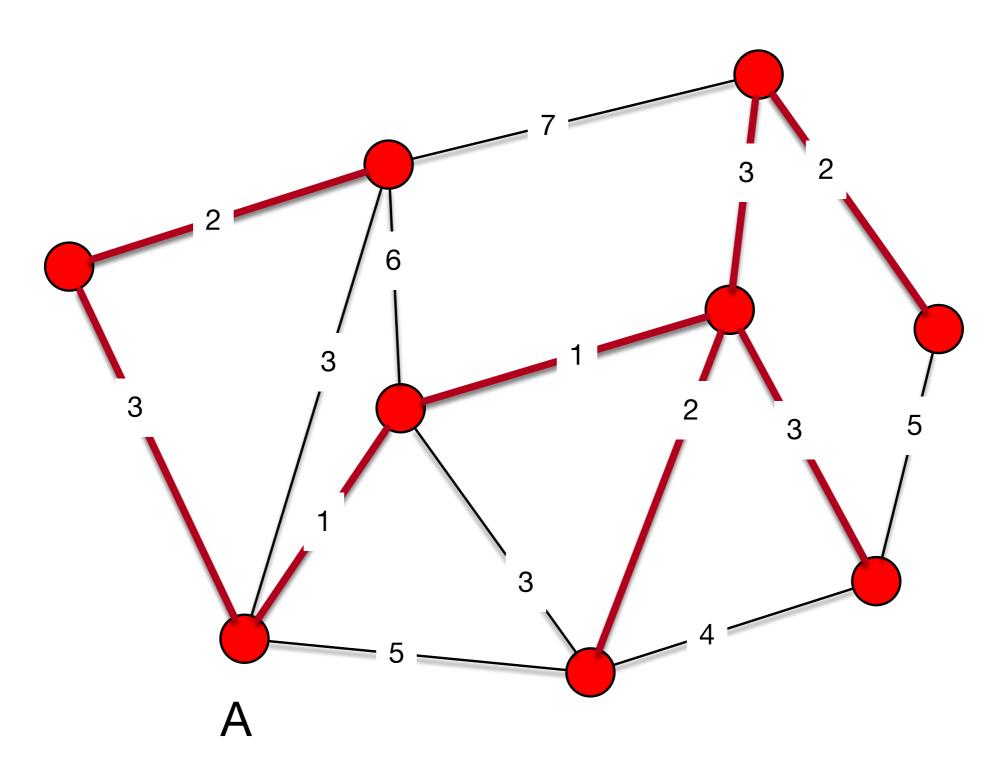












- Because Prim's algorithm only selects safe edges, it correctly calculates a minimum spanning tree
- The run-time of Prim's algorithm depends on the implementation of the priority heap
  - The best type is a Fibonacci heap
    - In which case the run time is  $O(|E| + V \log(|V|))$
  - Or we can use a normal priority heap which gives us
    - $O(E \log(V))$