Distributed Time

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- System clock
 - Precisely machined quartz crystal
 - Counter and Holding register
 - Each oscillation of quartz decrements counter
 - When counter gets to zero, generate interrupt
 - Counter is reloaded from holding register
 - Time is incremented

- On a single system
 - Absolute time does not really matter
 - Important are relative times
 - Example:
 - Make will recompile *.c files if their modified time is later than the corresponding *.o file

- Multiple CPU with their own clock
- Distributed systems
 - Need to deal with clock skew
- Is there a single notion of time?
 - Astronomical time
 - Atom clock time TAI
 - Leap seconds, UTC



- Clock synchronization algorithms
 - Cristian's algorithm
 - Ask time server for time
 - Determine time



- To determine most likely time given a value send by a time server:
 - Repeat several times
 - Record request send and answer received times (in local time)
 - Record answer received
 - Eliminate outliers
 - Calculate delta
 - Average delta
 - Adjust local time

$$\Delta = t_{\rm time\ server} - (t_{\rm received} + t_{\rm sent})/2$$

- Group quiz
 - Calculate clock adjustment

sent	received	value
300	350	410
450	495	555
600	750	620
800	845	915
1000	1055	1135
1200	1400	1590

- Berkeley Algorithm
 - Time daemon polls all machines asking for their time
 - Calculates average time
 - Tells all other machines how to adjust



- Absolute time is rarely used
 - Exceptions: time outs
- For distributed protocols:
 - Need Logical Time
 - ullet

- Lamport time stamps
 - "Happens before" relationship between events:
 - a <* b
 - Axioms:
 - a, b events in the same process, and a happens before b, then a<*b
 - If
- a message being sent
- b message being received
- then
 - a <* b

- Each system maintains its own logical time
 - Each local event advances the logical time by (at least one tick)
 - Each message is time-stamped
 - When a message is received, set local time to
 - MAX(local_time + 1, time_stamp + 1)
- Properties
 - Local events have different times

- Replica management
 - All replicas need to see the same sequence of updates



Totally Ordered Multicast

- Multicast in which all messages are delivered in the same order to receivers
 - Group of processes multicasting to each other
 - Each message is time-stamped
 - Messages are received in order sent
 - Messages are sent to everyone, including the sender
 - Messages are put in local queues ordered by timestamp
 - Receiver multicast acknowledgments to the other processes
 - Lamport clock algorithm assures that all messages have different timestamps
 - All processes eventually have the same messages in their queue

- Individual quiz:
 - Assume C1 and C2 send out update messages at the same time to replica servers R1 and R2

Vector Timestamps

- Lamport timestamps do not capture causality
- Vector timestamps better capture causality $V_i = [V_i[1], V_i[1], \dots V_i[n]]$
- Number of events that have occurred at process Pi:

$$V_i[i]$$

• Pi knows that k events have occurred at Pj if

$$V_i[j] = k$$

Vector Timestamps

- Process Pi increments Vi[i] whenever something local happens
- Process Pj receives message with Vj
 - Sets Vj[k] = MAX(Vi[k], Vj[k])

Vector Timestamps

- Bulletin board with several threads
 - Local events are sending of messages
 - Maintainer of the bulletin board only posts messages if it knows that all casually anterior messages have been received