

$$\mathbf{D} = \begin{pmatrix} x_{1,1} & x_{1,2} & \cdots & x_{1,d} \\ x_{2,1} & x_{2,2} & \cdots & x_{2,d} \\ x_{3,1} & x_{3,2} & \cdots & x_{3,d} \\ \cdots & & & \\ x_{n,1} & x_{n,2} & \cdots & x_{n,d} \end{pmatrix}$$