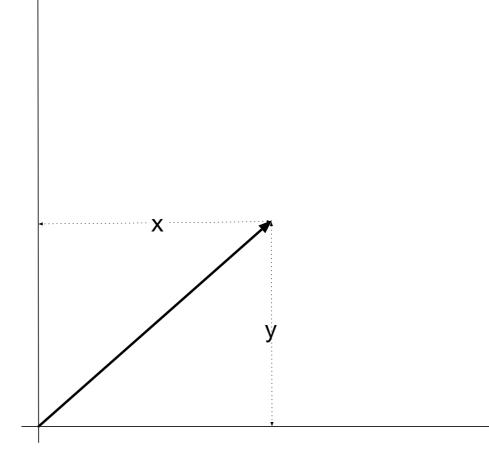
Repetition Classes

TwoDVector Class

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- TwoDVector:
 - encapsulates two components



 Define all the components of a class in the constructor (__init__ dunder)

```
class TwoDVector:
    def __init__(self, a, b):
        self.x = a
        self.y = b
```

- The str and repr dunders have only self as argument and return a string
- Usually, we use format

```
def __str__(self):
    return '({},{})'.format(self.x, self.y)
    def __repr__(self):
        return '<Vector self.x = {}, self.y = {}
>'.format(self.x, self.y)
```

• The str dunder is called when we communicate with the end user, for example in a print statement

- The repr dunder is used by the programmer
 - Usually contains more information
 - Will be returned by the shell

>>> TwoDVector(2,3)
<Vector self.x = 2, self.y = 3>
>>>

Overwriting functions

- Python has several standard functions that can be overwritten
 - __len__() for len()
 - __abs__() for abs()
- The absolute value of a vector is the square-root of the sum of squares of its coordinates

def __abs__(self):
 return math.sqrt(self.x**2+self.y**2)

Overwriting functions

 We call the absolute-value function using the abs function on an object of the class

```
>>> myvector = TwoDVector(-3,2)
>>> abs(myvector)
3.605551275463989
>>>
```

- Python numbers can be compared with <, >, <=, >=, ==, and !=
- We can implement these Boolean operators using dunder functions with magic names.
- In the context of a vector, comparisons other than for equality and inequality make no sense

It is traditional to use self and other as the names for the operands

def	eq(self, other):
	return self.x==other.x and self.y==other.y
def	ne(self, other):
	return self.x!=other.x or self.y!=other.y

- Python allows us to define our own versions of arithmetic operators
- We can say

```
>>> b = TwoDVector(2,1)
>>> a = TwoDVector(4,5)
>>> a+b
<Vector self.x = 6, self.y = 6>
```

- To create an addition, we use the __add__ dunder
- We need to return the result as a new object
 - In our case, creating a new Vector object

def __add__(self, other): return TwoDVector(self.x+other.x,self.y+other.y)

- To use the += operator, we overwrite __iadd___
 - This one modifies self, but also returns self

```
def __iadd_ (self, other):
        self.x += other.x
        self.y += other.y
        return self
```

>>> b = TwoDVector(2,1)
>>> a = TwoDVector(4,5)
>>> a+b
<Vector self.x = 6, self.y = 6>
>>> a += b
>>> print(a)
(6,6)
>>>

- Selftest:
 - Implement and try out subtraction

- Vectors do not have a traditional multiplication, but they have the "dot" product
 - $(a,b) \cdot (c,d) = ac + bd$
- The result of the dot multiplication is a scalar, not another vector
- But this is no problem, we just return a scalar for __mul__

def __mul__(self, other):
 return self.x*other.x+self.y*other.y

• Usage is no different then for normal operations

- When Python encounters an expression a+b
 - It first checks whether there is an __add__ dunder for a
 - Then it checks whether there is an __radd__ dunder for
 - It is not necessary that a or b are objects of the same class

• Vectors have a scalar multiplication

•
$$x \cdot (a, b) = (xa, xb)$$

- Notice that we traditionally write the scalar to the left and the vector to the right
- So we can use __rmul__ to implement scalar multiplication
 - We still need to return a new Vector

def __rmul__(self, nr):
 return TwoDVector(self.x*nr, self.y*nr)

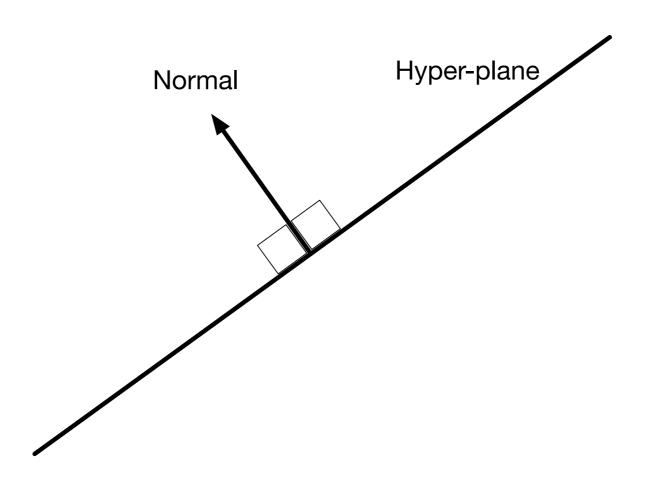
- If we try a *= 3 for a vector a, the __mul__ operation
 gets invoked, effectively calculating a = a*3
 - This results in an error, since an integer does not have x and y fields
- However, we can implement __imul__ and then it will work

```
def __imul__(self, other):
    self.x *= other
    self.y *= other
    return self
```

- Two-dimensional vectors have a rich set of functions
- We can rotate a vector by an angle θ using the formula:

$$\begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix}$$

• A reflection on a hyperplane is defined in terms of a normal, a vector standing orthogonal on the plane



- The formula for the reflection uses the dot-product
- *a* is the normal of the hyperplane

•
$$v \longrightarrow v - 2 \frac{v \cdot a}{a \cdot a} a$$

def reflect_by(self, other):

'''Reflection of self on hyperplane orthogonal to other'''
return self - 2*(self*other)/(other*other)*other